

Unsupervised learning of reflexive and action-based affordances to model adaptive navigational behavior

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Frontiers in neurorobotics

2010; 4:2

ARTICLE IDENTIFIERS

DOI: 10.3389/fnbot.2010.00002

PMID: 20485463

PMCID: PMC2871689

JOURNAL IDENTIFIERS

LCCN: 2009263101

pISSN: not available

eISSN: 1662-5218

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101477958

This article was identified from a query of the SafetyLit database.