

Single-Lane Cellular Automaton Model Considering Influence of Nearest Neighbor Vehicles and the Next-Nearest Neighbor Vehicles

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2006; 30(6):11-15

ARTICLE IDENTIFIERS

DOI: unavailable

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1673-0291

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.