

A co-evolutionary lane-changing trajectory planning method for automated vehicles based on the instantaneous risk identification

Wu J, Chen X, Bie Y, Zhou W.
Accident analysis and prevention
2022; 180:e106907

ARTICLE IDENTIFIERS

DOI: 10.1016/j.aap.2022.106907
PMID: 36455450
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79009842
pISSN: 0001-4575
eISSN: 1879-2057
OCLC ID: 01460775
CONS ID: not available
US National Library of Medicine ID: 1254476

This article was identified from a query of the SafetyLit database.