Maneuver-Based Trajectory Planning for Highly Autonomous Vehicles on Real Road With Traffic and Driver Interaction
IEEE transactions on intelligent transportation systems
2010; 11(3):589-606

ARTICLE IDENTIFIERS
DOI: 10.1109/TITS.2010.2046037
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS
LCCN: not available
pISSN: 1524-9050
eISSN: not available
OCLC ID: not available
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.