Control of distributed autonomous robotic systems using principles of pattern formation in nature and pedestrian behavior
Molnár P, Starke J.
IEEE transactions on systems, man, and cybernetics. Part B, cybernetics 2001; 31(3):433-435

ARTICLE IDENTIFIERS
DOI: 10.1109/3477.931538
PMID: 18244808
PMCID: not available

JOURNAL IDENTIFIERS
LCCN: not available
pISSN: 1083-4419
eISSN: 1941-0492
OCLC ID: not available
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.