

Control of distributed autonomous robotic systems using principles of pattern formation in nature and pedestrian behavior

Molnár P, Starke J.

IEEE transactions on systems, man, and cybernetics. Part B, cybernetics
2001; 31(3):433-435

ARTICLE IDENTIFIERS

DOI: 10.1109/3477.931538

PMID: 18244808

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1083-4419

eISSN: 1941-0492

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.