## Volunteer occupant kinematics during driver initiated and autonomous braking when driving in real traffic environments

Carlsson S, Davidsson J. Proceedings of the International Research Council on the Biomechanics of Injury conference 2011; 39:125-136

## **ARTICLE IDENTIFIERS**

DOI: unavailable PMID: unavailable PMCID: not available

## JOURNAL IDENTIFIERS

LCCN: not available pISSN: not available eISSN: 2235-3151 OCLC ID: not available CONS ID: not available US National Library of Medicine ID: not available

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