

Advanced fuzzy potential field method for mobile robot obstacle avoidance

Park JW, Kwak HJ, Kang YC, Kim DW.
Computational intelligence and neuroscience
2016; 2016:6047906

ARTICLE IDENTIFIERS

DOI: 10.1155/2016/6047906
PMID: 27123001
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2008244035
pISSN: 1687-5265
eISSN: 1687-5273
OCLC ID: not available
CONS ID: not available
US National Library of Medicine ID: 101279357

This article was identified from a query of the SafetyLit database.