

Analysis and design of a passive steering mechanism for a pedaled, self-balanced unicycle

Huang CF, Hong JH, Yeh TJ.

J. Mech. Robot.

2015; 8(1):e011006

ARTICLE IDENTIFIERS

DOI: 10.1115/1.4030652

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1942-4302

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.