

Optimal path planning for unmanned ground vehicles using potential field method and optimal control method

El Gindy M, Ren J, Mohamed A, Sharaf AM.
International journal of vehicle performance
2018; 4(1):1-14

ARTICLE IDENTIFIERS

DOI: 10.1504/IJVP.2018.10009700
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available
pISSN: 1745-3194
eISSN: 1745-3208
OCLC ID: not available
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.