

Research on PF-SLAM indoor pedestrian localization algorithm based on feature point map

Shi J, Ren M, Wang P, Meng J.

Micromachines (Basel)

2018; 9(6):e9060267

ARTICLE IDENTIFIERS

DOI: 10.3390/mi9060267

PMID: 30424200

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2012254626

pISSN: not available

eISSN: 2072-666X

OCLC ID: 652357628

CONS ID: not available

US National Library of Medicine ID: 101640903

This article was identified from a query of the SafetyLit database.