

Is more always better? The impact of vehicular trajectory completeness on car-following model calibration and validation

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Transportation research part B: methodological

2019; 120:49-75

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trb.2018.12.016

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79645158

pISSN: 0191-2615

eISSN: 1879-2367

OCLC ID: 4827986

CONS ID: sn 79002419

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.