

Human-like car-following model for autonomous vehicles considering the cut-in behavior of other vehicles in mixed traffic

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Accident analysis and prevention

2019; 132:e105260

ARTICLE IDENTIFIERS

DOI: 10.1016/j.aap.2019.105260

PMID: 31442924

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79009842

pISSN: 0001-4575

eISSN: 1879-2057

OCLC ID: 01460775

CONS ID: not available

US National Library of Medicine ID: 1254476

This article was identified from a query of the SafetyLit database.