

## **Occlusion-free road segmentation leveraging semantics for autonomous vehicles**

Wang K, Yan F, Zou B, Tang L, Yuan Q, Lv C.

Sensors (Basel)

2019; 19(21):s19214711

### **ARTICLE IDENTIFIERS**

DOI: 10.3390/s19214711

PMID: 31671547

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.