

Wearer-prosthesis interaction for symmetrical gait: a study enabled by reinforcement learning prosthesis control

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IEEE transactions on neural systems and rehabilitation engineering

2020; ePub(ePub):ePub

ARTICLE IDENTIFIERS

DOI: 10.1109/TNSRE.2020.2979033

PMID: 32149646

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2001214203

pISSN: 1534-4320

eISSN: 1558-0210

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.