## Human-like obstacle avoidance trajectory planning and tracking model for autonomous vehicles that considers the river's operation characteristics

Sun Q, Guo Y, Fu R, Wang C, Yuan W.

Sensors (Basel) 2020; 20(17):e4821

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s20174821

PMID: 32858979 PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115 pISSN: not available eISSN: 1424-8220 OCLC ID: 47250782 CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.