

## **PORF-DDPG: learning personalized autonomous driving behavior with progressively optimized reward function**

Chen J, Wu T, Shi M, Jiang W.

Sensors (Basel)

2020; 20(19):e5626

### **ARTICLE IDENTIFIERS**

DOI: 10.3390/s20195626

PMID: 33019643

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.