

A predictive perception model and control strategy for collision-free autonomous driving

Yoo J, Langari R.

IEEE transactions on intelligent transportation systems

2019; 20(11):4078-4091

ARTICLE IDENTIFIERS

DOI: 10.1109/TITS.2018.2880409

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1524-9050

eISSN: 1558-0016

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.