

# **Security robot for the prevention of workplace violence using the non-linear adaptive heuristic mathematical model**

Tao H, Arafatur Rahman M, Al-Saffar A, Zhang R, Salih SQ, Zain JM, Al-Hajri AAM.

Work

2021; ePub(ePub):ePub

## **ARTICLE IDENTIFIERS**

DOI: 10.3233/WOR-203419

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 91659126

pISSN: 1051-9815

eISSN: 1875-9270

OCLC ID: 22161995

CONS ID: not available

US National Library of Medicine ID: 9204382

This article was identified from a query of the SafetyLit database.