

Reproducing human arm strategy and its contribution to balance recovery through model predictive control

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Frontiers in neurorobotics

2021; 15:679570

ARTICLE IDENTIFIERS

DOI: 10.3389/fnbot.2021.679570

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2009263101

pISSN: not available

eISSN: 1662-5218

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101477958

This article was identified from a query of the SafetyLit database.