

A trajectory-tracking controller for improving the safety and stability of four-wheel steering autonomous vehicles

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Transport

2021; 36(2):147-163

ARTICLE IDENTIFIERS

DOI: 10.3846/transport.2021.14291

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1648-4142

eISSN: 1648-3480

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.