

# **Interactive and worst-case optimized robust control for potential application to guaranteeing roll stability for intelligent heavy vehicle**

Liu Y, Ji X, Yang K, He X, Nakano S.

International journal of automotive technology

2021; 22(5):1291-1303

## **ARTICLE IDENTIFIERS**

DOI: 10.1007/s12239-021-0113-4

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1229-9138

eISSN: 1976-3832

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.