

Position estimation in urban U-turn section for autonomous vehicles using multiple vehicle model and interacting multiple model filter

Choi S, Hong D.

International journal of automotive technology

2021; 22(6):1599-1607

ARTICLE IDENTIFIERS

DOI: 10.1007/s12239-021-0138-8

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1229-9138

eISSN: 1976-3832

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.