

# **Improved grip force prediction using a loss function that penalizes reward related neural information**

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Annual International Conference of the IEEE Engineering in Medicine and Biology Society.  
2022; 2022:2336-2339

## **ARTICLE IDENTIFIERS**

DOI: 10.1109/EMBC48229.2022.9871920

PMID: 36085700

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 2375-7477

eISSN: 2694-0604

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101763872

This article was identified from a query of the SafetyLit database.