A global path planning method for unmanned vehicle formation based on pilot-following method

Li ZH, Gao LD, Liu YY. Advances in transportation studies 2022; (SI 4):71-80

ARTICLE IDENTIFIERS

DOI: unavailable PMID: unavailable PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available pISSN: 1824-5463 eISSN: not available OCLC ID: not available CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.