

Path planning research of a UAV base station searching for disaster victims' location information based on deep reinforcement learning

Zhao J, Gan Z, Liang J, Wang C, Yue K, Li W, Li Y, Li R.

Entropy (Basel, Switzerland)

2022; 24(12):e1767

ARTICLE IDENTIFIERS

DOI: 10.3390/e24121767

PMID: 36554172

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 1099-4300

OCLC ID: 39088780

CONS ID: sn 98004425

US National Library of Medicine ID: 101243874

This article was identified from a query of the SafetyLit database.