

High-level motor planning allows flexible walking at different gait patterns in a neuromechanical model

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Frontiers in bioengineering and biotechnology

2022; 10:e959357

ARTICLE IDENTIFIERS

DOI: 10.3389/fbioe.2022.959357

PMID: 36568295

PMCID: PMC9772469

JOURNAL IDENTIFIERS

LCCN: 2014243446

pISSN: not available

eISSN: 2296-4185

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101632513

This article was identified from a query of the SafetyLit database.