Vehicle dynamics control system design by use of integrated control of front steering angle and driving/braking torque for a micro four in-wheelmotor vehicle

Yun S, Nishimura H, Murakami S. Transactions of Society of Automotive Engineers of Japan 2015; 46(2):399-406

ARTICLE IDENTIFIERS

DOI: 10.11351/jsaeronbun.46.399

PMID: unavailable PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available pISSN: 0287-8321 eISSN: 1883-0811 OCLC ID: 1076728522 CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.