

Evasion planning for autonomous intersection control based on an optimized conflict point control formulation

Kang D, Li Z, Levin MW.

Journal of transportation safety and security

2022; 14(12):2074-2110

ARTICLE IDENTIFIERS

DOI: 10.1080/19439962.2021.1998939

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2008216354

pISSN: 1943-9962

eISSN: 1943-9970

OCLC ID: 276986294

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.