

# **Real-time trajectory prediction method for intelligent connected vehicles in urban intersection scenarios**

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Sensors (Basel)  
2023; 23(6)

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s23062950  
PMID: 36991658  
PMCID: PMC10055911

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115  
pISSN: not available  
eISSN: 1424-8220  
OCLC ID: 47250782  
CONS ID: not available  
US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.