

# **An obstacle avoidance path planning and evaluation method for intelligent vehicles based on the B-spline algorithm**

Zhang Y, Wang P, Cui K, Zhou H, Yang J, Kong X.  
Sensors (Basel)  
2023; 23(19)

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s23198151  
PMID: 37836981  
PMCID: PMC10574840

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115  
pISSN: not available  
eISSN: 1424-8220  
OCLC ID: 47250782  
CONS ID: not available  
US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.