## Motion and geometry-related information fusion through a framework for object identification from a moving camera in urban driving scenarios

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Transportation research part C: emerging technologies

2023; 155:e104271

## **ARTICLE IDENTIFIERS**

DOI: 10.1016/j.trc.2023.104271

PMID: unavailable PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 93640664 pISSN: 0968-090X eISSN: 1879-2359 OCLC ID: 27960434 CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.