

An automatic driving trajectory planning approach in complex traffic scenarios based on integrated driver style inference and deep reinforcement learning

Liu Y, Diao S.

PLoS one

2024; 19(1):e0297192

ARTICLE IDENTIFIERS

DOI: 10.1371/journal.pone.0297192

PMID: 38271371

PMCID: PMC10810543

JOURNAL IDENTIFIERS

LCCN: 2006214532

pISSN: not available

eISSN: 1932-6203

OCLC ID: 228234657

CONS ID: not available

US National Library of Medicine ID: 101285081

This article was identified from a query of the SafetyLit database.