Observer-based event-triggered adaptive platooning control for autonomous vehicles with motion uncertainties

Xue Y, Wang C, Ding C, Yu B, Cui S.

Transportation research part C: emerging technologies

2024; 159:e104462

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trc.2023.104462

PMID: unavailable PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 93640664 pISSN: 0968-090X eISSN: 1879-2359 OCLC ID: 27960434 CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.