

# **Adaptive sliding mode based fault tolerant control of wheeled mobile robots**

Ayy?ld?z M, Tilki U.

Automatika

2023; 64(3):467-483

## **ARTICLE IDENTIFIERS**

DOI: 10.1080/00051144.2023.2190866

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2018205226

pISSN: 0005-1144

eISSN: 1848-3380

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.