

# **Trajectory tracking of four-wheel driving and steering autonomous vehicle under extreme obstacle avoidance condition**

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Vehicle system dynamics

2024; 62(3):601-622

## **ARTICLE IDENTIFIERS**

DOI: 10.1080/00423114.2023.2186249

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0042-3114

eISSN: 1744-5159

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.