

Error compensation method for pedestrian navigation system based on low-cost inertial sensor array

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Sensors (Basel)
2024; 24(7):e2234

ARTICLE IDENTIFIERS

DOI: 10.3390/s24072234
PMID: 38610444
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002242115
pISSN: not available
eISSN: 1424-8220
OCLC ID: 47250782
CONS ID: not available
US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.