

Robust calibration technique for precise transformation of low-resolution 2D LiDAR points to camera image pixels in intelligent autonomous driving systems

Rajesh R, Manivannan PV.

Vehicles (Basel)

2024; 6(2):711-727

ARTICLE IDENTIFIERS

DOI: 10.3390/vehicles6020033

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 2624-8921

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.