

# **Human-machine shared steering control under high-speed emergency obstacle avoidance scenarios**

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Transportation research record  
2024; 2678(7):70-85

## **ARTICLE IDENTIFIERS**

DOI: 10.1177/03611981231203221  
PMID: unavailable  
PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 74032372  
pISSN: 0361-1981  
eISSN: 2169-4052  
OCLC ID: 01259379  
CONS ID: not available  
US National Library of Medicine ID: 101481512

This article was identified from a query of the SafetyLit database.